

# Lipschitz Continuity and Approximate Equilibria

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# Background

## Strategic-Form game

- $M$  players
- $S_i$  of pure strategies for each player  $i \in [M]$
- $U_i$  payoff function for each player  $i \in [M]$

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- Player  $i$  picks a probability distribution  $x_i$  over the set of pure strategies  $S_i$
  - Strategy profile  $X = (x_1, \dots, x_M)$
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  - $U_i(x_i, X_{-i})$  payoff for the player  $i$  under the profile  $X$   
**The payoff function  $U_i(x_i, X_{-i})$  is linear in  $x_i$**

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## Definition ( $\epsilon$ -Nash equilibrium)

A strategy profile is an  $\epsilon$ -Nash equilibrium if:

no player can gain more than  $\epsilon$  by a unilateral deviation

**(additive notion of approximation)**

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## Theorem (Daskalakis, Goldberg, Papadimitriou 2006)

*If there is an FPTAS for computing an  $\epsilon$ -Nash for 4 player games, then **PPAD** = **P**.*

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## Theorem (Chen, Deng, Teng 2006)

*If there is an FPTAS for computing an  $\epsilon$ -Nash of a bimatrix game, then  $\text{PPAD} = \text{P}$ .*



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## Definition ( $\epsilon$ -Nash equilibrium)

A strategy profile is an  $\epsilon$ -Nash equilibrium if:

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## Theorem (Rubinstein 2016)

*If there is a PTAS for computing an  $\epsilon$ -Nash of a bimatrix game, then **EndOfTheLine** can be solved faster than exponential time.*

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## Theorem (Lipton, Markakis, Mehta (LMM) 2003)

*For every constant  $\epsilon > 0$ , an  $\epsilon$ -Nash can be computed in **quasi-polynomial time**.*

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*For every constant  $\epsilon > 0$ , an  $\epsilon$ -Nash can be computed in **quasi-polynomial time**.*

All these results apply on **strategic-form** games.

# Lipschitz Games

## $\lambda_p$ -Lipschitz game

- $M$  players
- $S_i$  is the convex hull of  $n$  vectors in  $\mathbb{R}^d$
- $T_i(\mathbf{x}_i, \mathbf{X}_{-i})$  utility function for each player  $i \in [M]$ ,

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## $\lambda_p$ -Lipschitz game

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- $S_i$  is the convex hull of  $n$  vectors in  $\mathbb{R}^d$   
(continuous action space)
- $T_i(\mathbf{x}_i, \mathbf{X}_{-i})$  utility function for each player  $i \in [M]$ ,  
where function  $T_i(\mathbf{x}_i, \mathbf{X}_{-i})$  is  $\lambda_p$ -Lipschitz continuous  
w.r.t.  $\mathbf{x}_i$  when  $\mathbf{X}_{-i}$  is fixed.

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## Definition ( $\lambda_p$ -Lipschitz)

A function  $f : \mathbf{A} \rightarrow \mathbb{R}$ , with  $\mathbf{A} \subseteq \mathbb{R}^d$  is  $\lambda_p$ -Lipschitz continuous if for every  $\mathbf{x}$  and  $\mathbf{y}$  in  $\mathbf{A}$ , it is true that  $|f(\mathbf{x}) - f(\mathbf{y})| \leq \lambda \cdot \|\mathbf{x} - \mathbf{y}\|_p$ .

# Lipschitz Games: examples

## Concave Games

Rosen (Econometrica 65)

## Risk Games

Fiat, Papadimitriou (SAGT 10)

Mavronicolas, Monien (TCS 16)

## Biased Games

Caragiannis, Kurokawa, Procaccia (AAAI 15)

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- Concave and Biased Games **always** possess an equilibrium
- Equilibrium existence for Risk Games is **NP-complete**



# Our results

- Efficient algorithms for computing  $\epsilon$ -equilibria in  $\lambda_p$ -Lipschitz games for every constant  $\epsilon > 0$ , or decide that the game does **not** possess one.

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- Efficient algorithms for computing  $\epsilon$ -equilibria in  $\lambda_p$ -Lipschitz games for every constant  $\epsilon > 0$ , or decide that the game does **not** possess one.
- Polynomial-time algorithms for computing constant approximate equilibria for three classes of biased games.

# The QPTAS of LMM

## Existence

In any  $n \times n$  bimatrix game, any  $\epsilon > 0$  and  $k \geq O\left(\frac{\ln n}{\epsilon^2}\right)$ , there exists a  $k$ -uniform strategy profile that is an  $\epsilon$ -NE.

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## Computation

Find such a profile in quasi-polynomial time by exhaustive search over all  $k$ -uniform strategy profiles (time  $n^{O\left(\frac{\ln n}{\epsilon^2}\right)}$ ).

# $k$ -uniform strategies

$$X = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\} \subset \mathbb{R}^d$$

***conv***( $X$ ): convex hull of  $X$

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$\text{conv}(X)$ : convex hull of  $X$

## Definition

A vector  $\mathbf{y} \in \text{conv}(X)$  is said to be  **$k$ -uniform** with respect to  $X$  if there exists a size  $k$  multiset  $\mathbf{S}$  of  $[n]$  such that  $\mathbf{y} = \frac{1}{k} \sum_{i \in \mathbf{S}} \mathbf{x}_i$ .

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## Definition

A strategy profile is said to be  **$k$ -uniform** if the strategy for every player is a  **$k$ -uniform** vector.

# Our result

## Theorem 1 (Existence)

In any  $\lambda_p$ -Lipschitz game that possess an equilibrium and any  $\epsilon > 0$ , there is a  $k$ -uniform strategy profile, with  $k = \frac{16M^2\lambda^2p}{\epsilon^2}$  that is an  $\epsilon$ -equilibrium.



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- $\lambda_p$ -Lipschitz continuity is crucial for the existence
- In the proof we utilize a recent result of Barman (STOC 15)

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- Hard to compute the approximation guarantee of a  $\mathbf{k}$ -uniform strategy profile.
- Hard to compute best responses ( $\max_{x_i} T_i(x_i, X_{-i})$ )
- We compute **approximate** best responses using  $\mathbf{k}$ -uniform strategies.

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## Theorem 2 (Computation)

For any  $\lambda_p$ -Lipschitz game  $L$  in time  $O(Mn^{Mk+I})$ , we can either compute a  $\epsilon$ -equilibrium, or decide that  $L$  does not possess an exact equilibrium, where  $k = O\left(\frac{\lambda^2 Mp}{\epsilon^2}\right)$  and  $I = O\left(\frac{\lambda^2 p}{\epsilon^2}\right)$ .

# Bimatrix games

		II	
		<i>c</i>	<i>d</i>
I	<i>a</i>	0.3 1	0.8 0
	<i>b</i>	1 0.1	0.5 1

- Two players: row, column
- Each player has  $n$  pure strategies
- $R, C$  are  $n \times n$  matrices
- Row player plays  $x$ , column player plays  $y$
- Payoff functions
  - Row:  $x^T R y$
  - Column:  $x^T C y$

# Penalty Games

- Extension of bimatrix games
- Payoff functions
  - Row:  $T_r(\mathbf{x}, \mathbf{y}) = \mathbf{x}^T \mathbf{R} \mathbf{y} - f_r(\mathbf{x})$
  - Column:  $T_c(\mathbf{x}, \mathbf{y}) = \mathbf{x}^T \mathbf{C} \mathbf{y} - f_c(\mathbf{y})$



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$\mathcal{P}_{\lambda_p}$ : penalty games where  $f_r(\mathbf{x})$  and  $f_c(\mathbf{y})$  are  $\lambda_p$ -Lipschitz continuous

# Our result

## Theorem 3 (Existence)

For any penalty game in the class  $\mathcal{P}_{\lambda_p}$  that possesses an equilibrium, any  $\epsilon > 0$ , and any  $k \in \frac{\Omega(\lambda^2 \log n)}{\epsilon^2}$ , there exists a  $k$ -uniform strategy profile that is an  $\epsilon$ -equilibrium.

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## Theorem 4 (Computation)

In any penalty game  $\mathcal{P}_{\lambda_p}$  and any  $\epsilon > 0$ , in quasi polynomial time we can either compute a  $\epsilon$ -equilibrium, or decide that  $\mathcal{P}_{\lambda_p}$  does not possess an exact equilibrium.

# Biased Games

- Subclass of penalty games
- Base strategies:  $\mathbf{s}$  and  $\mathbf{t}$
- Payoff functions
  - Row:  $T_r(\mathbf{x}, \mathbf{y}) = \mathbf{x}^T \mathbf{R} \mathbf{y} - d_r \cdot \|\mathbf{x} - \mathbf{s}\|_p$
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$$T_r(\mathbf{x}, \mathbf{y}) = \mathbf{x}^T \mathbf{R} \mathbf{y} - \frac{1}{3} \cdot \left\| \mathbf{x} - \left[ \frac{1}{2}, \frac{1}{2} \right]^T \right\|_2^2$$

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  - Column:  $T_c(\mathbf{x}, \mathbf{y}) = \mathbf{x}^T C \mathbf{y} - d_c \cdot \|\mathbf{y} - \mathbf{t}\|_p$

We study three norms:  $L_1, L_2^2, L_\infty$

## Approximation guarantee

$$L_1 : \quad 2/3$$

$$L_2^2 : \quad 5/7$$

$$L_\infty : \quad 2/3$$

# A polynomial time approximation algorithm

Generalization of DMP algorithm



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Generalization of DMP algorithm

## The Base Algorithm

- 1 Compute a best response  $\mathbf{y}^*$  against  $\mathbf{s}$ .
- 2 Compute a best response  $\mathbf{x}$  against  $\mathbf{y}^*$ .
- 3 Set  $\mathbf{x}^* = \delta \cdot \mathbf{s} + (1 - \delta) \cdot \mathbf{x}$ , for some  $\delta \in [0, 1]$ .
- 4 Return the strategy profile  $(\mathbf{x}^*, \mathbf{y}^*)$ .

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**Not trivial how to compute best responses**

We derive simple combinatorial algorithms for computing best responses.

# Simple best response algorithm

## Best Response Algorithm for $L_\infty$ penalty

- 1 For all  $i \in \mathcal{L}$ , set  $\mathbf{x}_i = \mathbf{0}$ .
- 2 If  $\mathcal{P} \leq |\mathcal{H}| \cdot \mathbf{s}_{\max}$ , then set  $\mathbf{x}_i = \mathbf{s}_i + \frac{\mathcal{P}}{|\mathcal{H}|}$  for all  $i \in \mathcal{H}$  and  $\mathbf{x}_j = \mathbf{s}_j$  for  $j \in \mathcal{M}$ .
- 3 Else if  $\mathcal{P} < |\mathcal{H} \cup \mathcal{M}| \cdot \mathbf{s}_{\max}$ , then
  - Set  $\mathbf{x}_i = \mathbf{s}_i + \mathbf{s}_{\max}$  for all  $i \in \mathcal{H}$ .
  - Set  $k = \lfloor \frac{\mathcal{P} - |\mathcal{H}| \cdot \mathbf{s}_{\max}}{\mathbf{s}_{\max}} \rfloor$ .
  - Set  $\mathbf{x}_i = \mathbf{s}_i + \mathbf{s}_{\max}$  for all  $i \leq |\mathcal{H}| + k$ .
  - Set  $\mathbf{x}_{|\mathcal{H}|+k+1} = \mathbf{s}_{|\mathcal{H}|+k+1} + \mathcal{P} - (|\mathcal{H}| + k) \cdot \mathbf{s}_{\max}$ .
  - Set  $\mathbf{x}_j = \mathbf{s}_j$  for all  $|\mathcal{H}| + k + 2 \leq j \leq |\mathcal{H}| + |\mathcal{M}|$ .
- 4 Else set  $\mathbf{x}_i = \mathbf{s}_i + \frac{\mathcal{P}}{|\mathcal{H} \cup \mathcal{M}|}$  for all  $i \in \mathcal{H} \cup \mathcal{M}$ .

# Open questions

- Exact complexity for Lipschitz and biased games?  
*PPAD* is not suitable. *FIXP*?
- Better polynomial-time approximation algorithms
- Tractable cases? (Zero sum biased games)

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**THANK YOU!**