

Robot Games with States in Dimension One

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University of Liverpool, UK

10th International Workshop on Reachability Problems

Introduction

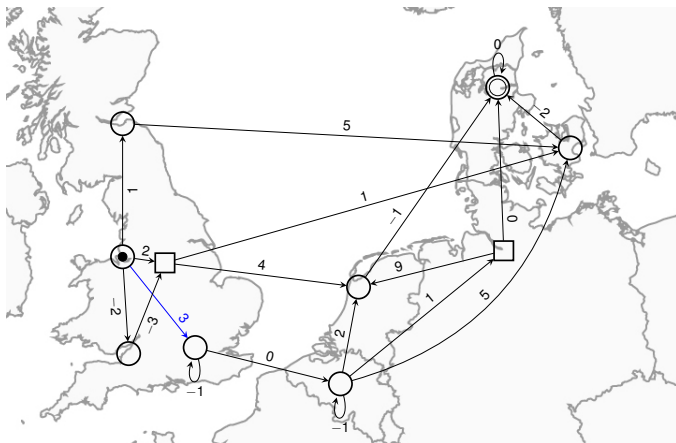
Counter reachability games



Stress level

0

Counter reachability games



Stress level

0

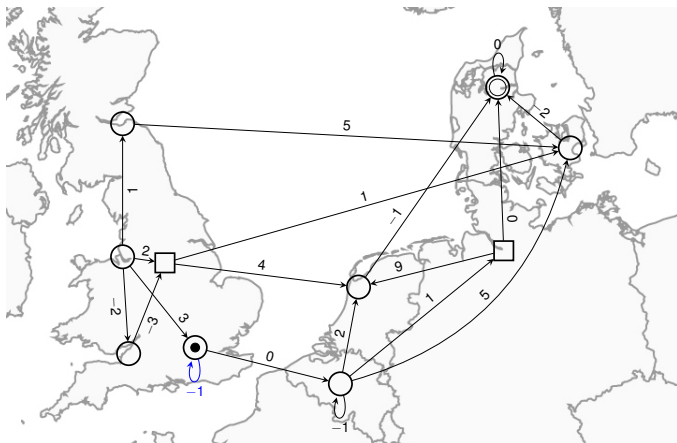
Counter reachability games



Stress level

0 → 3

Counter reachability games



Stress level

0 → 3

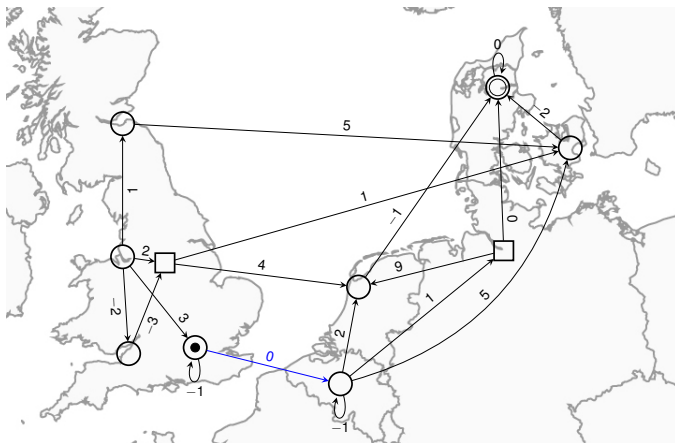
Counter reachability games



Stress level

0 → 3 → 2

Counter reachability games



Stress level

0 → 3 → 2

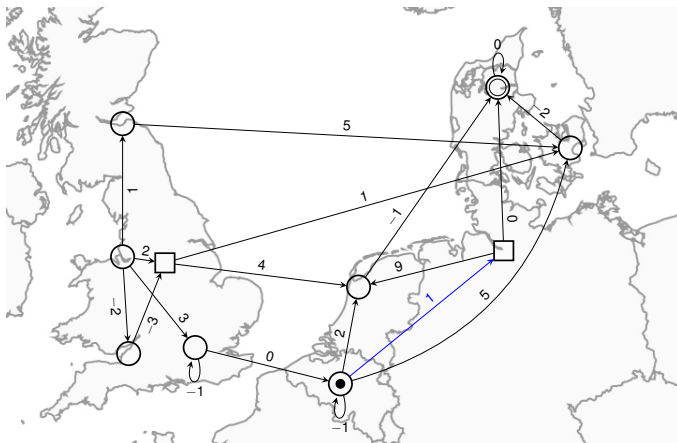
Counter reachability games



Stress level

0 → 3 → 2 → 2

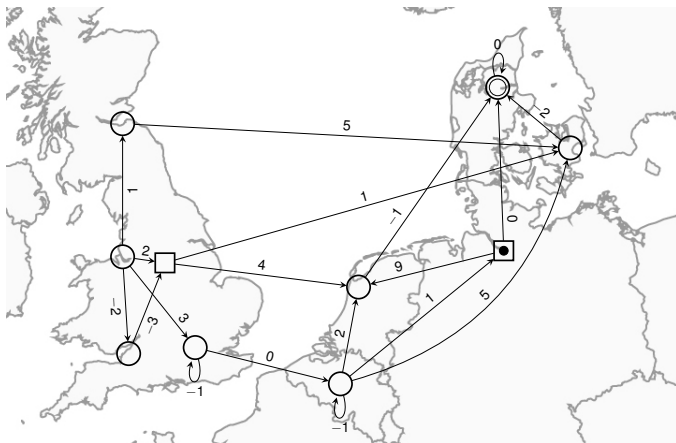
Counter reachability games



Stress level

0 → 3 → 2 → 2

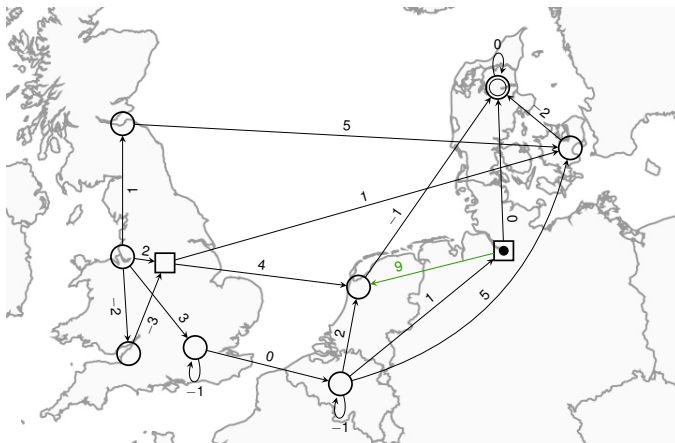
Counter reachability games



Stress level

0 → 3 → 2 → 2 → 3

Counter reachability games



Stress level

0 → 3 → 2 → 2 → 3

Counter reachability games



Stress level

0 → 3 → 2 → 2 → 3 → 12

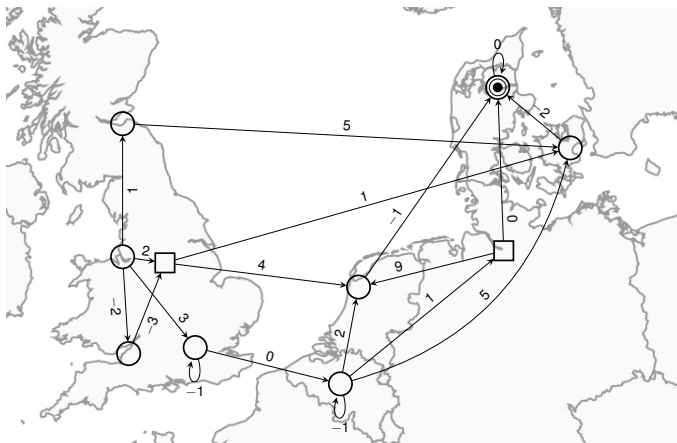
Counter reachability games



Stress level

0 → 3 → 2 → 2 → 3 → 12

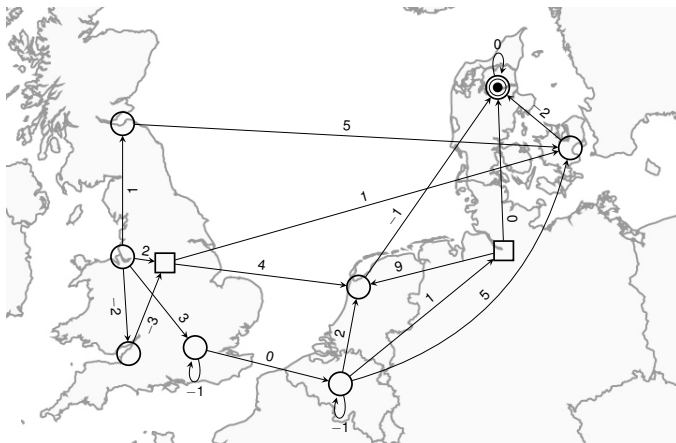
Counter reachability games



Stress level

0 → 3 → 2 → 2 → 3 → 12 → 13

Counter reachability games



Stress level

0 → 3 → 2 → 2 → 3 → 12 → 13 → ...

Counter reachability games



Stress level

0

Counter reachability games



Stress level

0

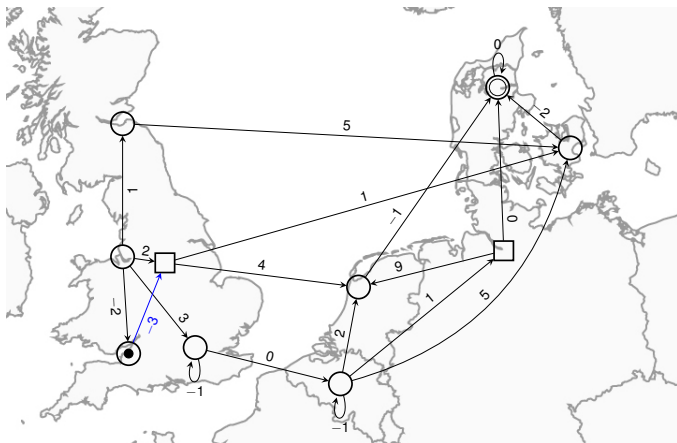
Counter reachability games



Stress level

0 → -2

Counter reachability games



Stress level

0 → -2

Counter reachability games



Stress level

0 → -2 → -5

Counter reachability games



Stress level

0 → -2 → -5

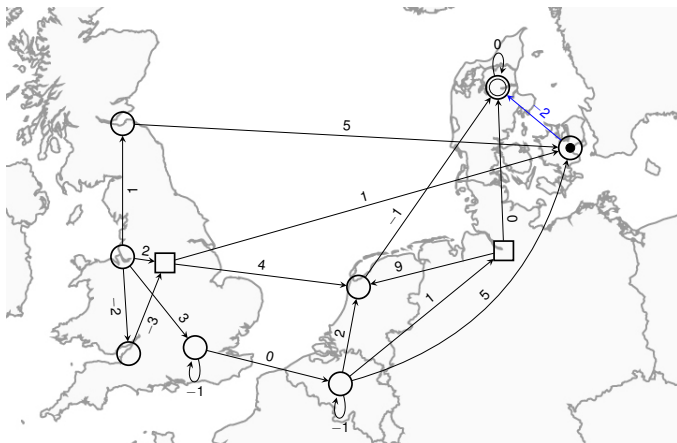
Counter reachability games



Stress level

0 → -2 → -5 → -4

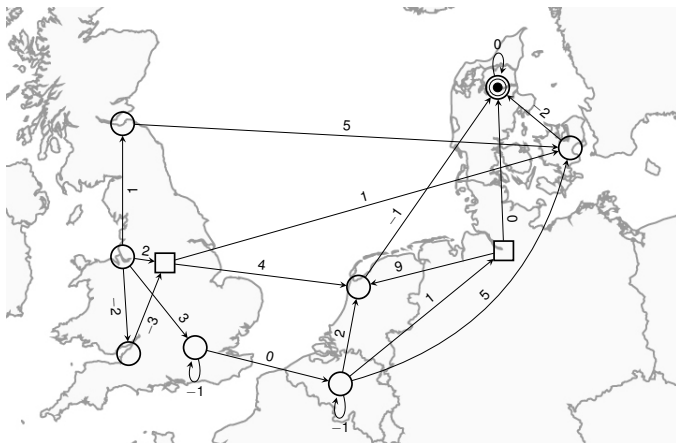
Counter reachability games



Stress level

0 → -2 → -5 → -4

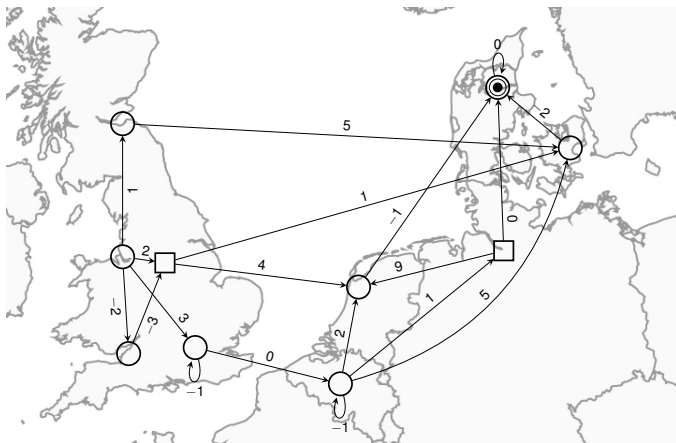
Counter reachability games



Stress level

0 → -2 → -5 → -4 → -6

Counter reachability games



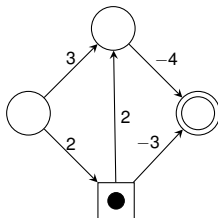
Stress level

0 → -2 → -5 → -4 → -6 → ...

Definitions

Counter reachability games

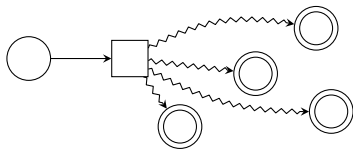
- Played on a labeled directed graph $G = (V, E)$ with edges labeled by $\mathbf{x} \in \mathbb{Z}^n$.
- Two players: **Eve** (○), **Adam** (□).
- A **configuration** $[v, \mathbf{z}] \in V \times \mathbb{Z}^n$.
- A successor configuration is $[v', \mathbf{z} + \mathbf{z}']$, where $[v, \mathbf{z}', v'] \in E$ and the owner of v chose it.
- The **initial** and **target** configurations.
- A **play** is a finite or an infinite sequence of configurations.
- **Eve wins** if the target configuration is reachable in a play starting from the initial configuration. Otherwise Adam wins.



Counter reachability games

A winning strategy

Eve has a **winning strategy** if the target configuration is reachable for every choice of Adam.



The decision problem

Given a graph $G = (V, E)$, initial and target configurations, $[v_0, \mathbf{z}_0]$ and $[v_f, (0, \dots, 0)]$. Does there exist a winning strategy for Eve to reach $[v_f, (0, \dots, 0)]$ from $[v_0, \mathbf{z}_0]$?

Counter reachability games

The decision problem

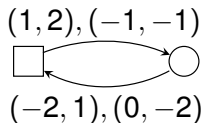
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Known for counter reachability games:

One-dimensional	EXPSpace -complete
Two-dimensional	Undecidable

Robot games

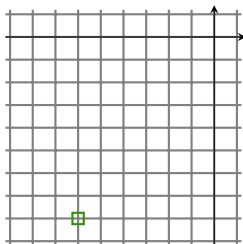
What if we have a simpler graph?



- Proposed by Doyen and Rabinovich in 2011.
- **EXPTIME**-complete in dimension one [\[Arul, Reichert, QAPL 2013\]](#).
- Undecidable in dimension two [\[N., Potapov, Reichert, MFCS 2016\]](#).

Another way to look at robot games

- Played on integer lattice \mathbb{Z}^n .
- Adam and Eve move a token on the lattice.
- Eve's goal is to reach $(0, \dots, 0)$. Adam's goal is to avoid it.

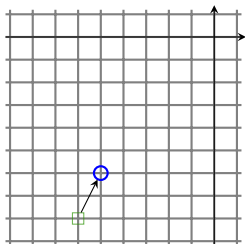


Adam's moves: $\{(1, 2), (2, 0)\}$

Eve's moves: $\{(2, 2), (1, 4)\}$

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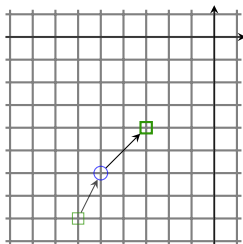


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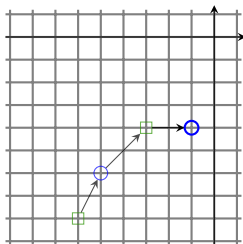


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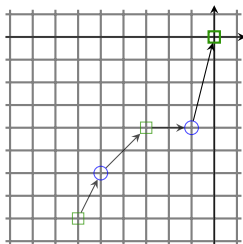


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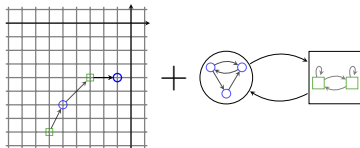


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Eve's moves: $\{(2, 2), (1, 4)\}$

Robot games with states

- A mix between counter reachability games and robot games.
- Robot games but players have internal states as well.
- Undecidable in dimension two [N., Potapov, Reichert, MFCS 2016].



Known results

Game	Dimension	
	1	≥ 2
counter reachability games	EXSPACE -complete	U
robot games with states	?	U
robot games	EXPTIME -complete	U

Known results

Game	Dimension	
	1	≥ 2
counter reachability games	EXSPACE -complete	U
robot games with states	?	U
robot games	EXPTIME -complete	U

Theorem

*Whether Eve has a winning strategy in a one-dimensional robot game with states is **EXSPACE**-complete.*

Robot games with states

Inherited complexity bounds

Lemma

*Deciding winner is **EXPTIME**-hard.*

Lemma

*Deciding winner is in **EXPSPACE**.*

Inherited complexity bounds

Lemma

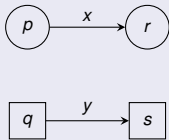
Deciding winner is **EXPTIME**-hard.

Lemma

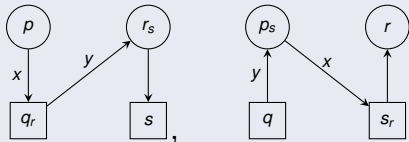
Deciding winner is in **EXPSPACE**.

Proof.

In RGS:

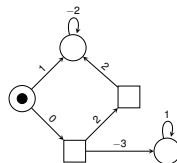


In CRG:



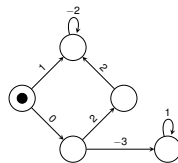
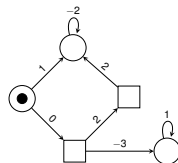
Proof idea

- Given a one-dimensional CRG G .
- wlog $\deg(\square) \leq 2$.
- Construct a robot game with states where
 - Eve simulates the whole graph.
 - Adam tells which choice he would have made in the original CRG.

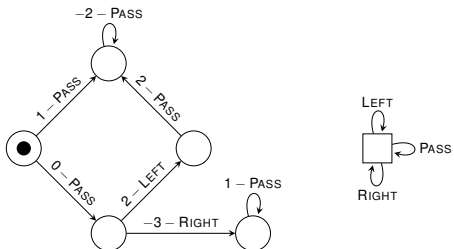


Proof idea

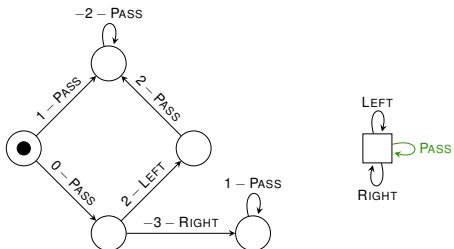
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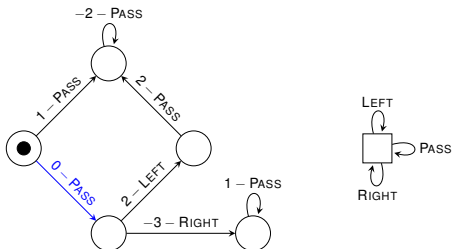
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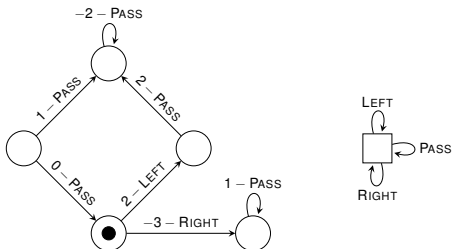
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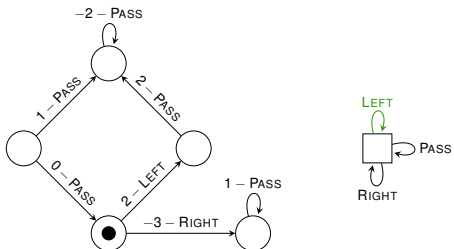
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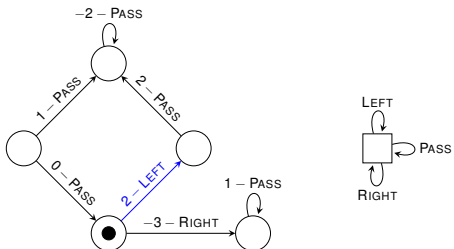
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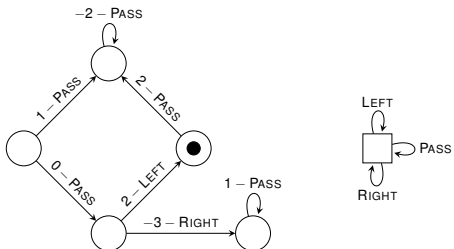
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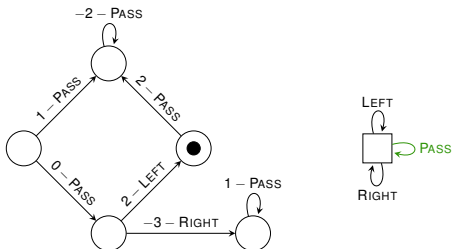
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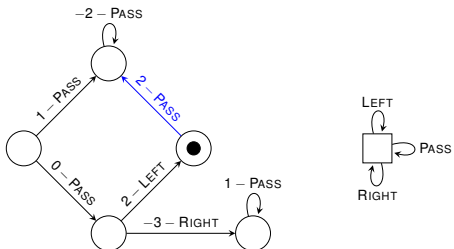
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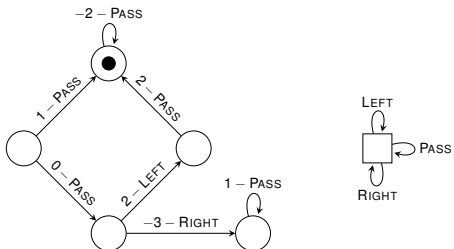
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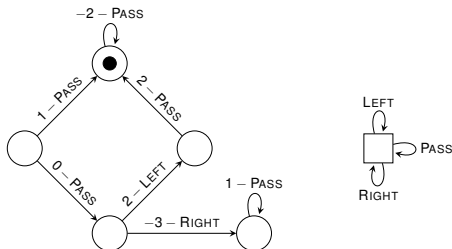
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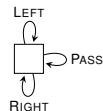
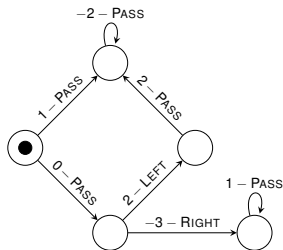
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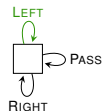
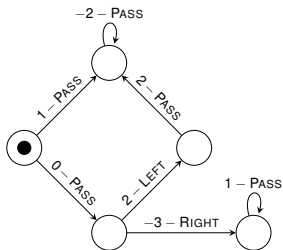
Lemma

If both players play correctly, then the winner in the RGS is the same as the winner in the CRG.

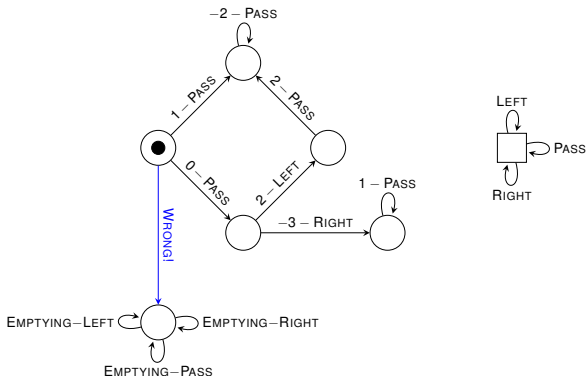
What if they don't play correctly?



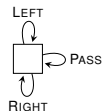
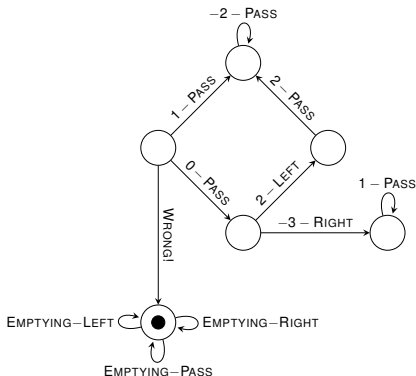
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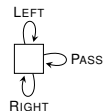
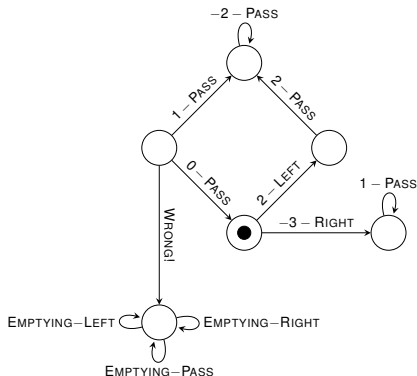
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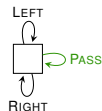
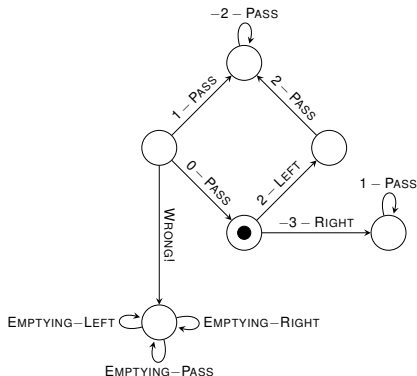
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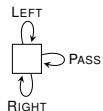
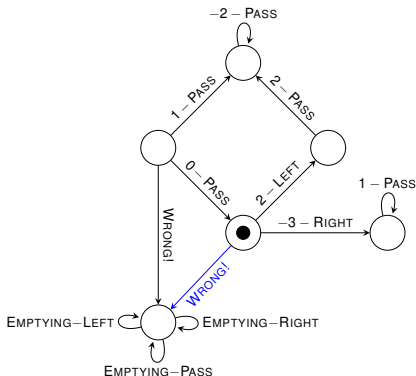
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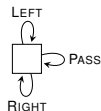
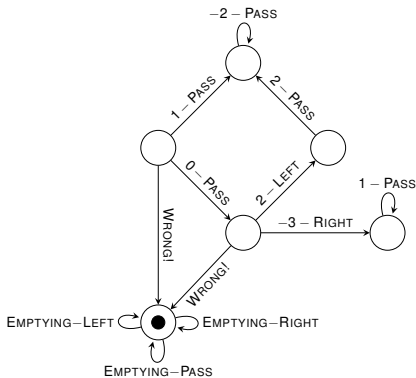
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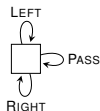
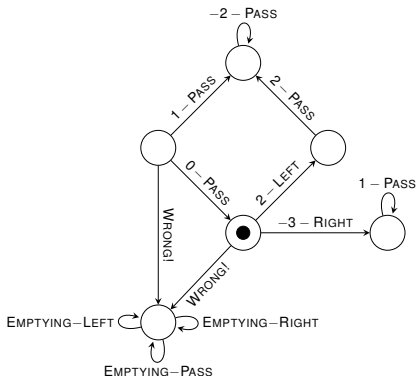
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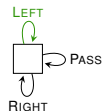
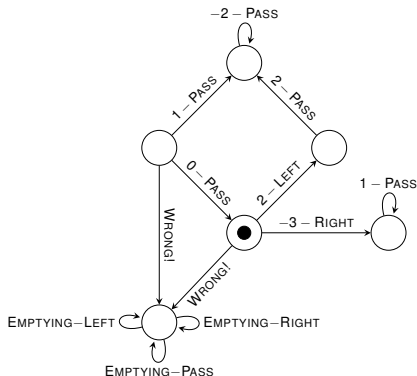
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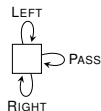
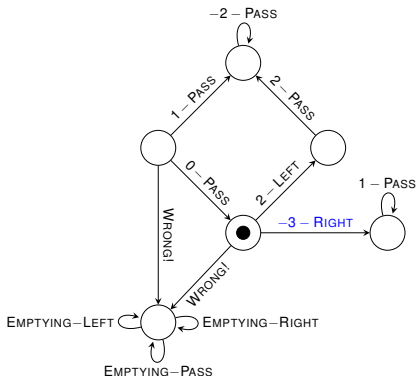
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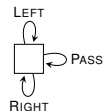
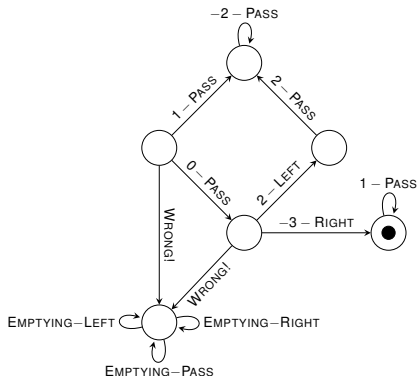
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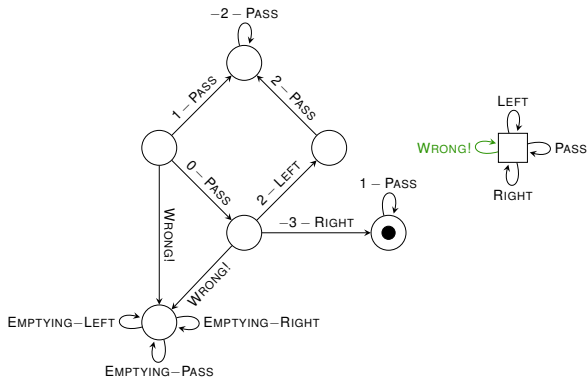
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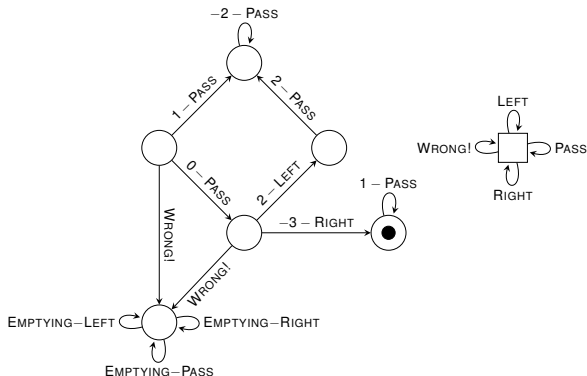
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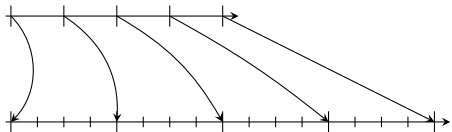
Lemma

If one of the players plays incorrectly, then the opponent is the winner.

What are PASS, LEFT, RIGHT, etc?

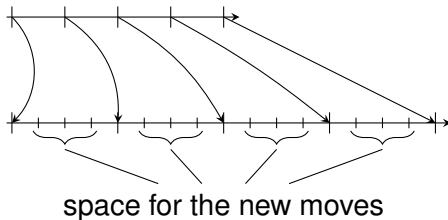


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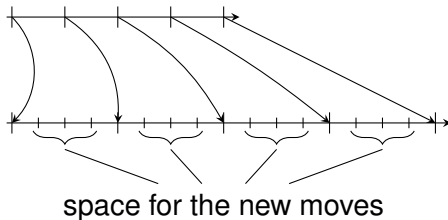
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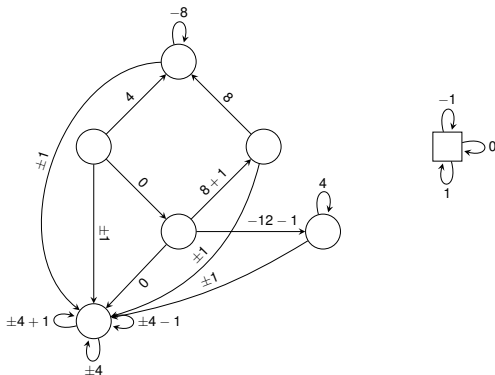
- The original values are multiplied by 4.

What are PASS, LEFT, RIGHT, etc?



- The original values are multiplied by 4.
- LEFT, RIGHT and WRONG! modify the value mod 4.
- PASS is 0.

The result



Theorem

Whether Eve has a winning strategy in a one-dimensional robot game with states is **EXPSpace**-complete.

Flat robot games with states

Effect of states

		Eve	
		stateless	states
Adam	stateless	EXPTIME-c	EXPSPACE-c
	states	?	EXPSPACE-c

Effect of states

		Eve	
		stateless	states
Adam	stateless	EXPTIME-c	EXPSPACE-c
	states	?	EXPSPACE-c

What if Adam's states are flat?

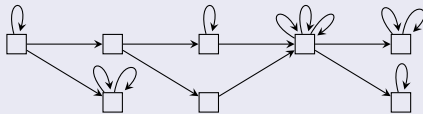
Effect of states

		Eve	
		stateless	states
Adam	stateless	EXPTIME-c	EXPSpace-c
	states	?	EXPSpace-c

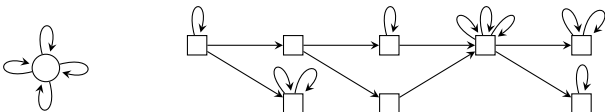
What if Adam's states are flat?

Flat automata

The underlying graph is directed acyclic graph with self-loop.



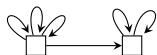
Flat robot games with states



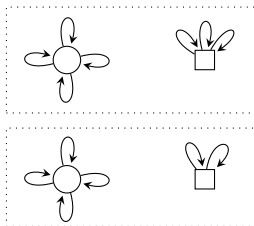
Theorem

*Deciding who has a winning strategy in a one-dimensional flat robot game with states is **EXPTIME**-complete.*

Proof idea

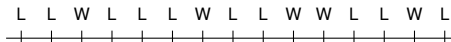
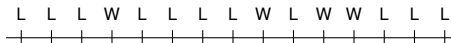
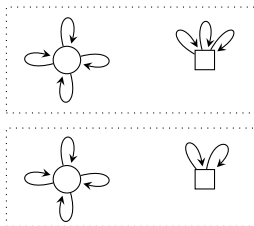


Proof idea



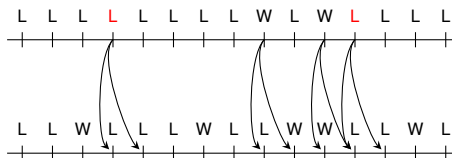
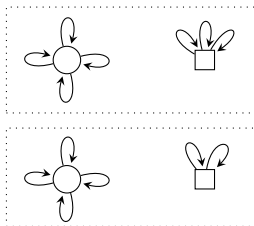
- As there exists a linear order, we can consider several stateless games that are connected.

Proof idea



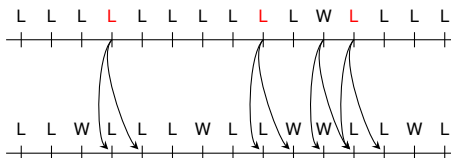
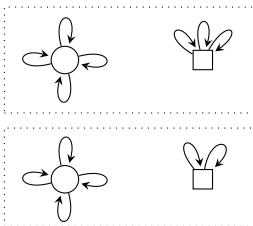
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- Check which winning values of the first game become losing when moving to the second game.

Proof idea



- As there exists a linear order, we can consider several stateless games that are connected.
- The algorithm for robot games gives a description of the winning values for Eve.
- Check which winning values of the first game become losing when moving to the second game.
- Check how new losing values affect other winning values.

Which values become losing?

Check which winning values of the first game become losing when moving to the second game.

Check how new losing values affect other winning values.

Which values become losing?

Check which winning values of the first game become losing when moving to the second game.

Simple case analysis.

Check how new losing values affect other winning values.

Both are doable in **PTIME** because the winning sets in robot games are (essentially)

L L L W L L L L W L W W L L L W L L W L L W L L W L

Finite interval where w's appear $\{w \in d\mathbb{Z} \mid w > b\}$

Which values become losing?

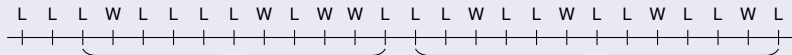
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Simple case analysis.

Check how new losing values affect other winning values.

We can construct an equivalent game on a graph where winning values are computed using the attractor construction.

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$L \ L \ L \ W \ L \ L \ L \ L \ W \ L \ W \ W \ L \ L \ L \ W \ L \ L \ W \ L \ L \ W \ L \ L \ W \ L$

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Conclusion

Summary

Theorem

Given one-dimensional robot games with states. Deciding which player has a winning strategy is **EXPSpace**-complete.

Game	Dimension	
	1	≥ 2
counter reachability games	EXPSpace -complete	U
robot games with states	?	U
flat robot games with states	?	?
robot games	EXPTIME -complete	U

Summary

Theorem

Given one-dimensional robot games with states. Deciding which player has a winning strategy is **EXPSPACE**-complete.

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robot games with states	EXPSPACE -complete	U
flat robot games with states	EXPTIME -complete	?
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Future work

- Investigate further what kind of state structure increases the complexity.
- Decidability of stateless VASS games.

Thank you for your attention!