

# COMP108 Algorithmic Foundations

## Dynamic Programming

Prudence Wong

<http://www.csc.liv.ac.uk/~pwong/teaching/comp108/201617>

## Dynamic programming an efficient way to implement some divide and conquer algorithms

### Learning outcomes

- Understand the basic idea of dynamic programming
- Able to apply dynamic programming to compute Fibonacci numbers
- Able to apply dynamic programming to solve the assembly line scheduling problem

### Fibonacci numbers ...

### Problem with recursive method

Fibonacci number  $F(n)$

$$F(n) = \begin{cases} 1 & \text{if } n = 0 \text{ or } 1 \\ F(n-1) + F(n-2) & \text{if } n > 1 \end{cases}$$

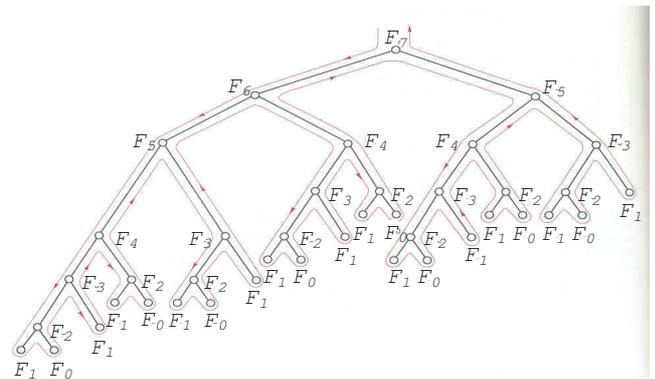
n	0	1	2	3	4	5	6	7	8	9	10
F(n)	1	1	2	3	5	8	13	21	34	55	89

### The execution of $F(7)$

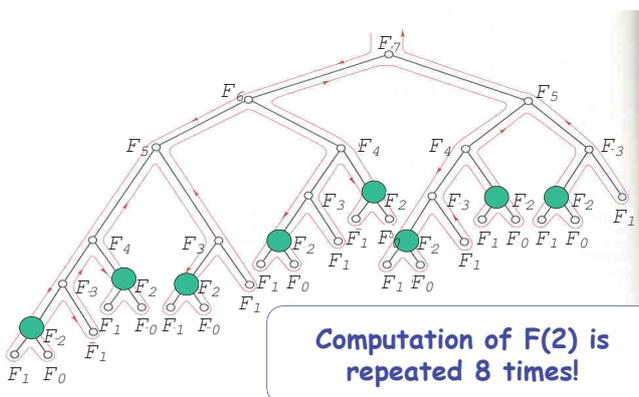
Pseudo code for the recursive algorithm:

```

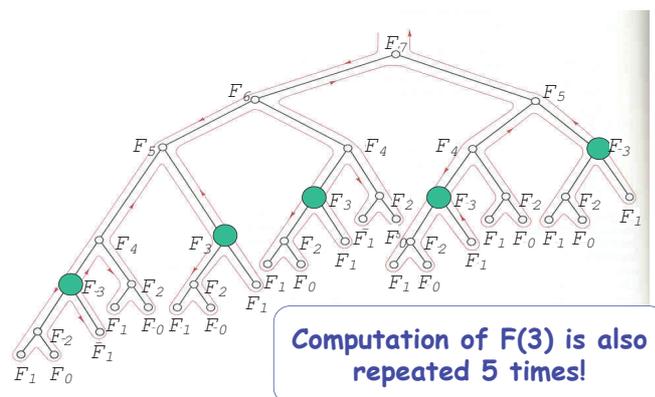
Procedure F(n)
  if n==0 or n==1 then
    return 1
  else
    return F(n-1) + F(n-2)
    
```



### The execution of $F(7)$

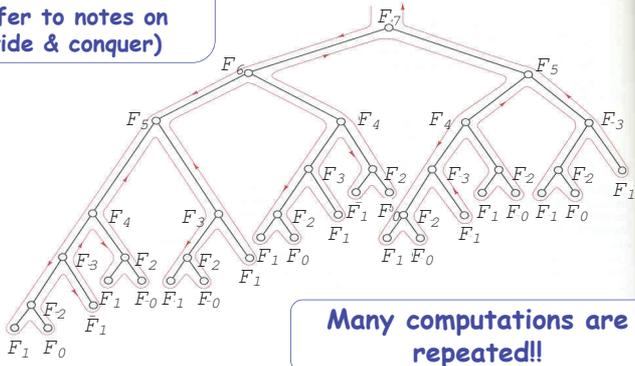


### The execution of $F(7)$



# The execution of F(7)

**How long it takes?**  
exponential time  
(refer to notes on divide & conquer)



# Idea for improvement

## Memorization:

- Store F(i) somewhere after we have computed its value
- Afterward, we don't need to re-compute F(i); we can retrieve its value from our memory.

```

Procedure F(n)
  if (v[n] < 0) then
    v[n] = F(n-1)+F(n-2)
  return v[n]
    
```

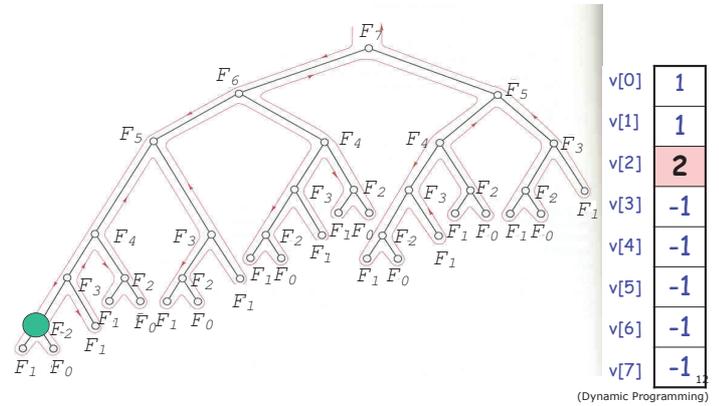
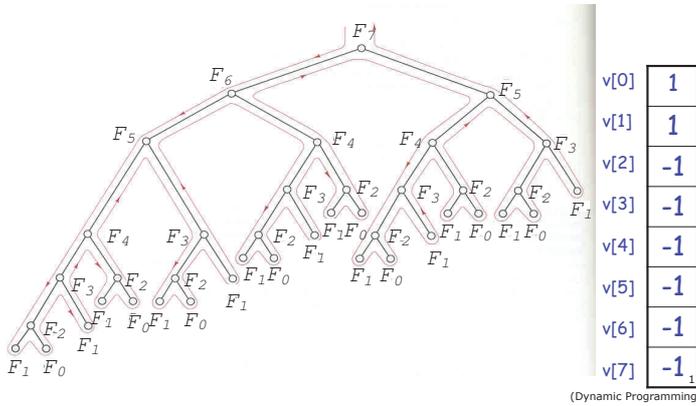
```

Main
  set v[0] = v[1] = 1
  for i = 2 to n do
    v[i] = -1
  output F(n)
    
```

[ ] refers to array  
( ) is parameter for calling a procedure

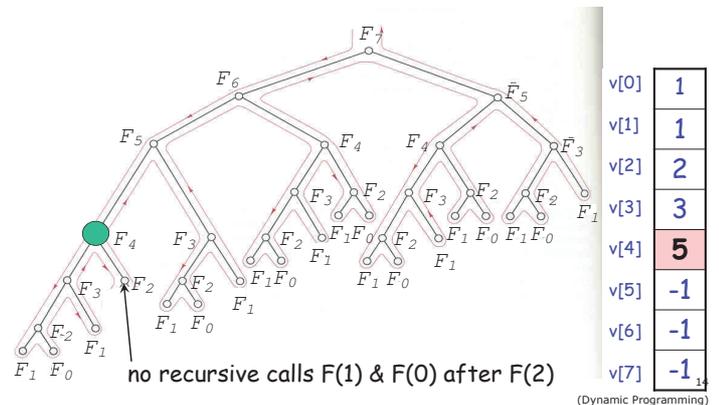
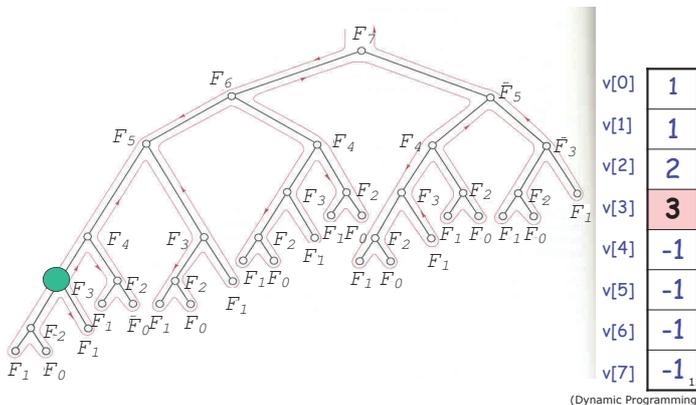
## Look at the execution of F(7)

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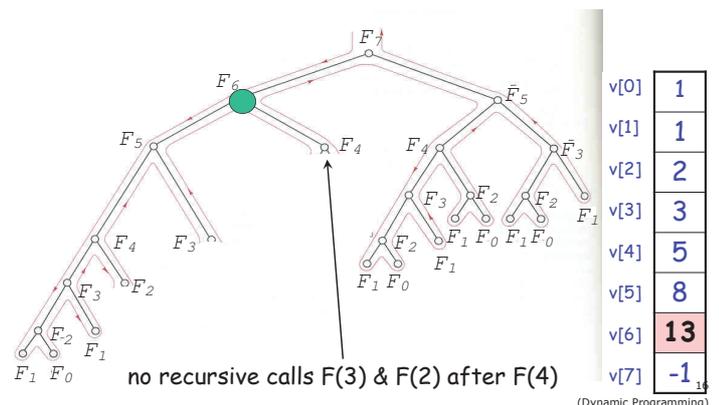
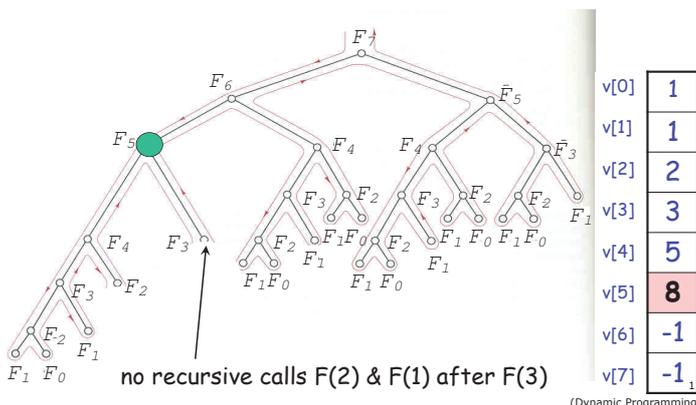
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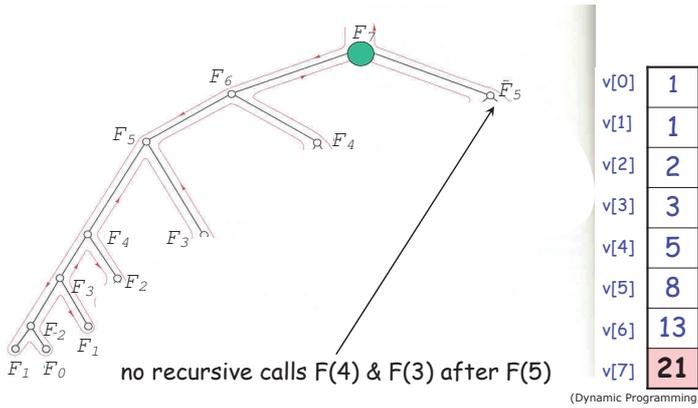


## Look at the execution of F(7)

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# Look at the execution of F(7)



# Can we do even better?

## Observation

- > The 2nd version still makes many function calls, and each wastes time in parameters passing, dynamic linking, ...
- > In general, to compute F(i), we need F(i-1) & F(i-2) only

## Idea to further improve

- > Compute the values in bottom-up fashion.
- > That is, compute F(2) (we already know F(0)=F(1)=1), then F(3), then F(4)...

This new implementation saves lots of overhead.

```

Procedure F(n)
  Set A[0] = A[1] = 1
  for i = 2 to n do
    A[i] = A[i-1] + A[i-2]
  return A[n]
    
```

# Recursive vs DP approach

## Recursive version:

```

Procedure F(n)
  if n==0 or n==1 then
    return 1
  else
    return F(n-1) + F(n-2)
    
```

Too Slow!  
exponential

## Dynamic Programming version:

```

Procedure F(n)
  Set A[0] = A[1] = 1
  for i = 2 to n do
    A[i] = A[i-1] + A[i-2]
  return A[n]
    
```

Efficient!  
Time complexity is O(n)

# Summary of the methodology

- > Write down a formula that relates a solution of a problem with those of sub-problems. E.g.  $F(n) = F(n-1) + F(n-2)$ .
- > Index the sub-problems so that they can be **stored** and **retrieved** easily in a table (i.e., array)
- > Fill the table in some **bottom-up** manner; start filling the solution of the smallest problem.
- > This ensures that when we solve a particular sub-problem, the solutions of all the smaller sub-problems that it depends are available.

For historical reasons, we call such methodology

**Dynamic Programming.**

In the late 40's (when computers were rare), programming refers to the "tabular method".

# Exercise

Consider the following function

$$G(n) = \begin{cases} 1 & \text{if } 0 \leq n \leq 2 \\ G(n-1) + G(n-2) + G(n-3) & \text{if } n > 2 \end{cases}$$

1. Write a recursive procedure to compute G(n)
2. Draw the execution tree of computing G(6) recursively
3. Using dynamic programming, write a pseudo code to compute G(n) efficiently
4. What is the time complexity of your algorithm?

# Exercise

$$G(n) = \begin{cases} 1 & \text{if } 0 \leq n \leq 2 \\ G(n-1) + G(n-2) + G(n-3) & \text{if } n > 2 \end{cases}$$

## Recursive version:

```

Procedure G(n)
  if ... then
    return ??
  else return ??
    
```

## Dynamic Programming version:

```

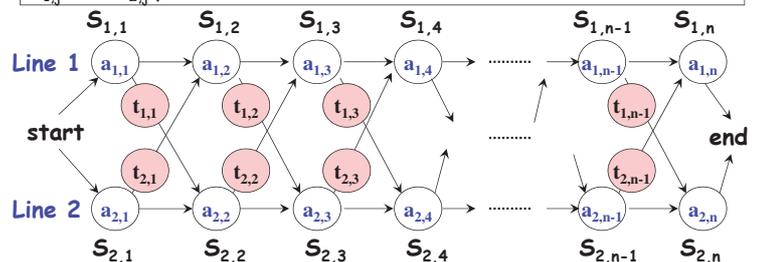
Procedure G(n)
    
```

O(??)

# Assembly line scheduling ...

# Assembly line scheduling

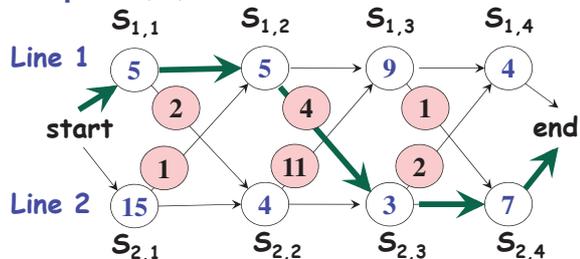
2 assembly lines, each with n stations ( $S_{i,j}$ : line i station j)  
 $S_{1,j}$  and  $S_{2,j}$  perform same task but time taken is different



$a_{i,j}$ : assembly time at  $S_{i,j}$   
 $t_{i,j}$ : transfer time after  $S_{i,j}$

**Problem:** To determine which stations to go in order to **minimize** the total time through the n stations

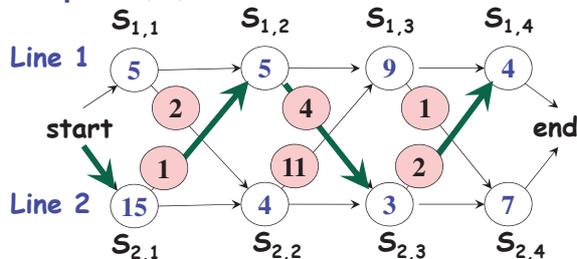
### Example (1)



stations chosen:  $s_{1,1}$     $s_{1,2}$     $s_{2,3}$     $s_{2,4}$   
 time required: 5   5   4   3   7 = 24

25  
(Dynamic Programming)

### Example (2)

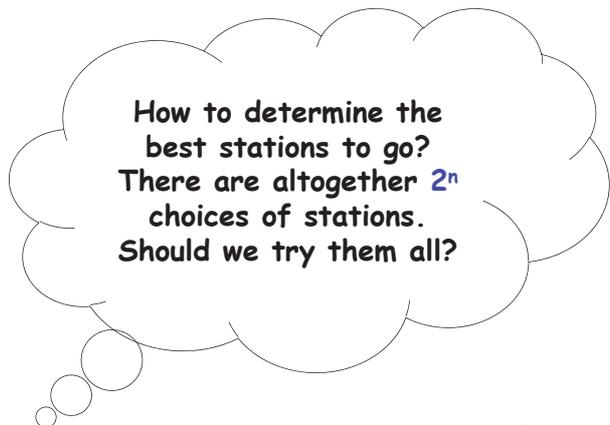


stations chosen:  $s_{1,1}$     $s_{1,2}$     $s_{2,3}$     $s_{2,4}$   
 time required: 5   5   4   3   7 = 24

stations chosen:  $s_{2,1}$     $s_{1,2}$     $s_{2,3}$     $s_{1,4}$   
 time required: 15   1   5   4   3   2   4 = 34

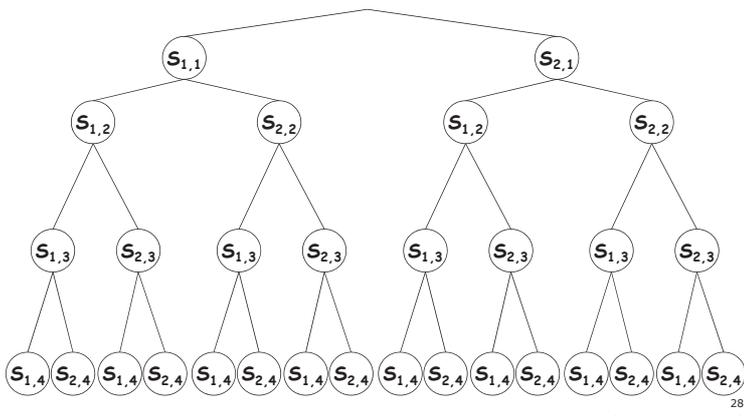
26  
(Dynamic Programming)

### Example (2)



27  
(Dynamic Programming)

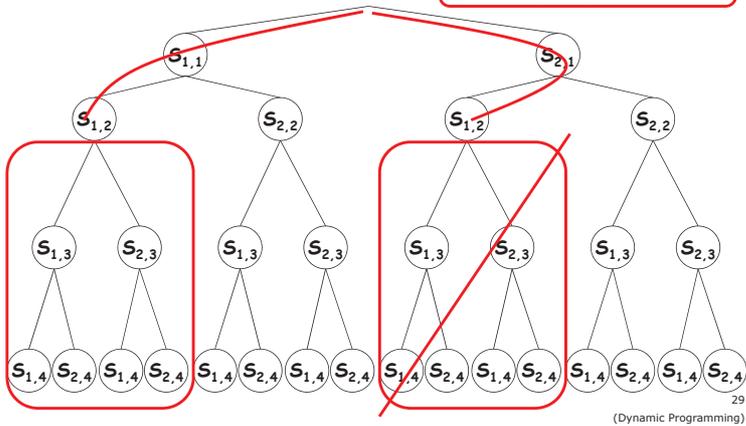
### All possible choices



28  
(Dynamic Programming)

### All possible choices

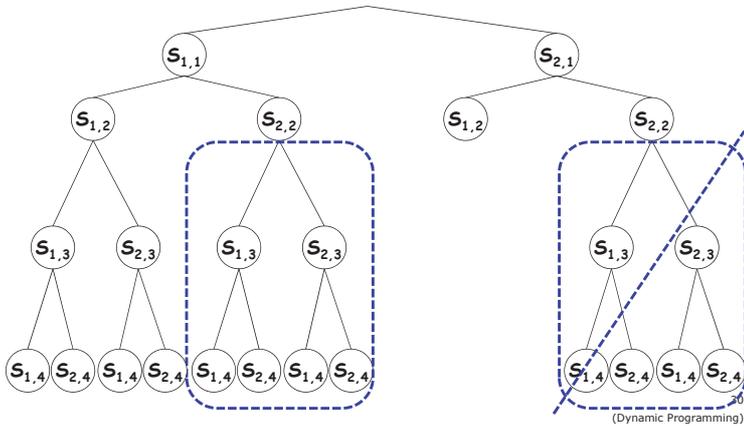
The two subtrees cost the same, only one path is needed.



29  
(Dynamic Programming)

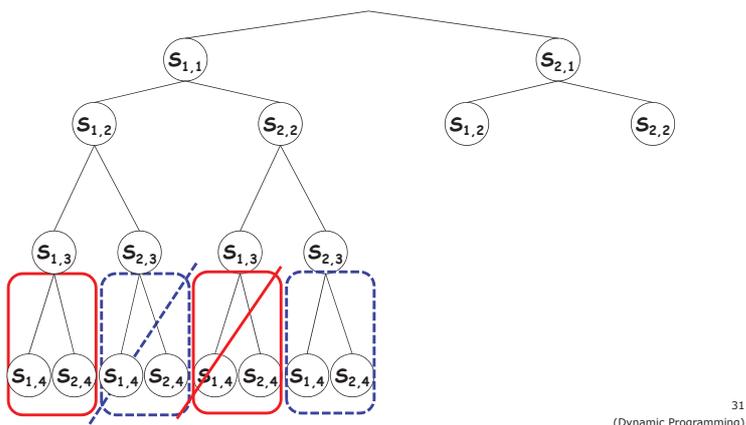
### All possible choices

Similarly, ...



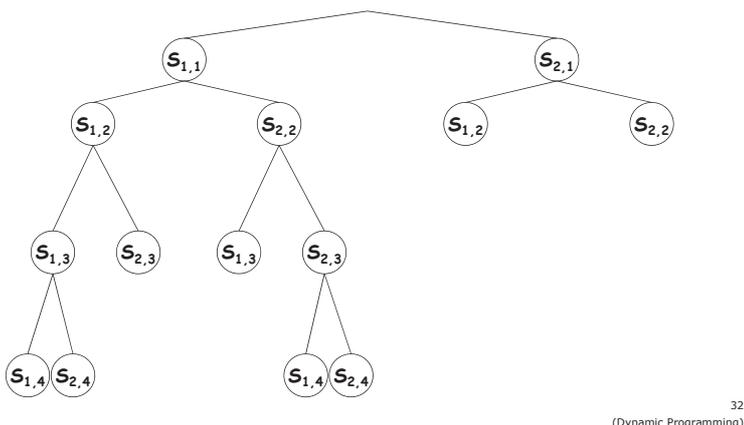
30  
(Dynamic Programming)

### All possible choices



31  
(Dynamic Programming)

### All possible choices



32  
(Dynamic Programming)

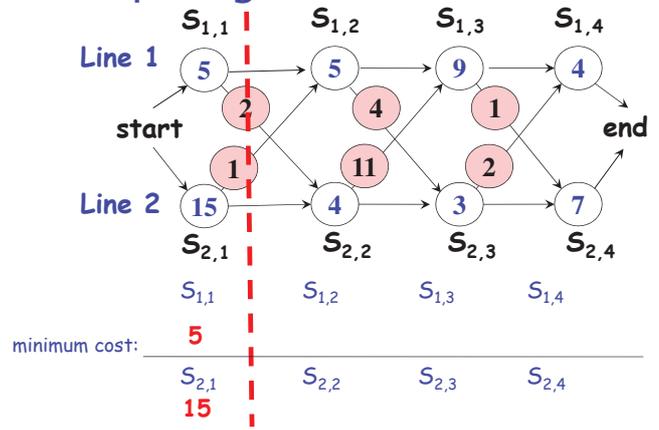
# Good news: Dynamic Programming

- We **don't** need to try all possible choices.
- We can make use of **dynamic programming**:
  1. If we can compute the fastest ways to get thro' station  $S_{1,n}$  and  $S_{2,n}$ , then the faster of these two ways is the overall fastest way.
  2. To compute the fastest ways to get thro'  $S_{1,n}$  (similarly for  $S_{2,n}$ ), we need to know the fastest way to get thro'  $S_{1,n-1}$  and  $S_{2,n-1}$
  3. In general, we want to know the fastest way to get thro'  $S_{1,j}$  and  $S_{2,j}$ , for all  $j$ .

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(Dynamic Programming)

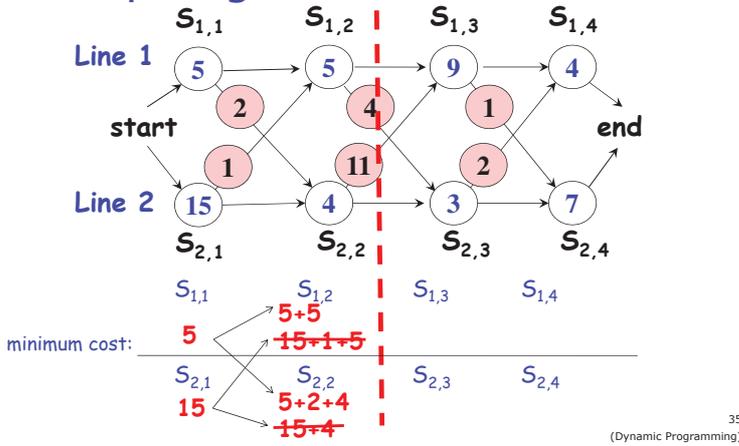
# Example again



34

(Dynamic Programming)

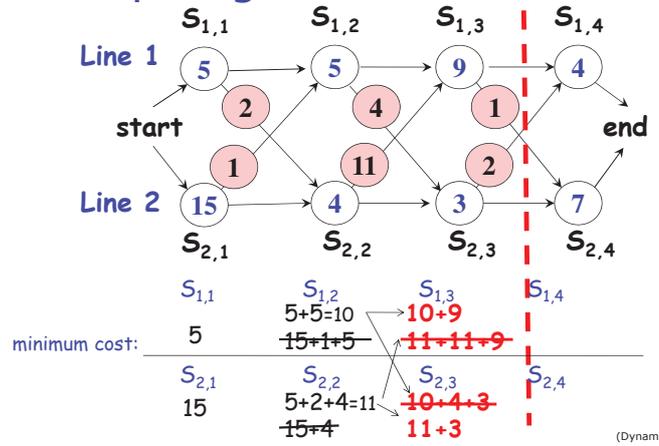
# Example again



35

(Dynamic Programming)

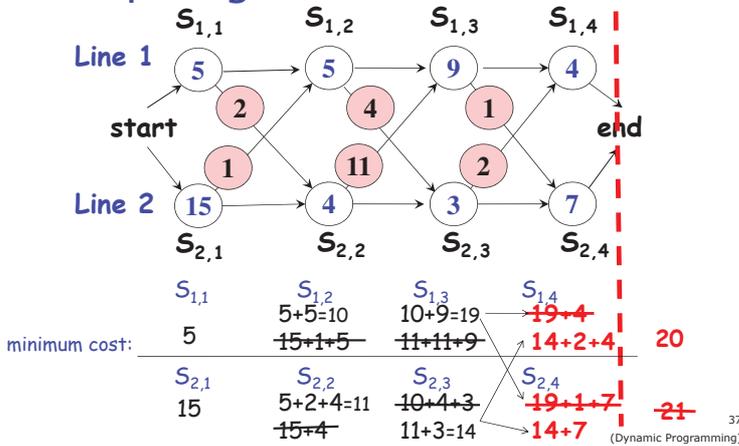
# Example again



36

(Dynamic Programming)

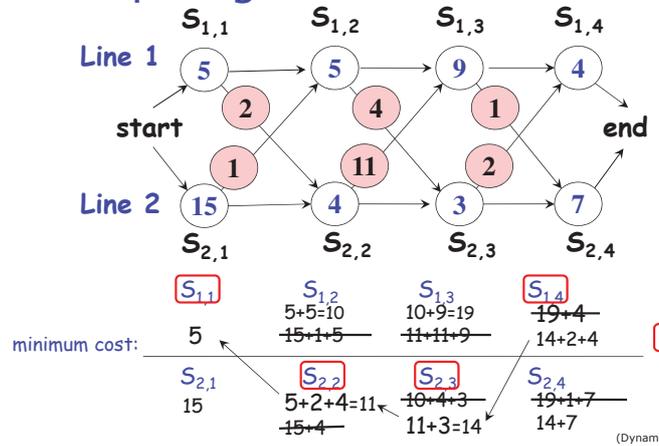
# Example again



37

(Dynamic Programming)

# Example again



38

(Dynamic Programming)

# A dynamic programming solution

What are the sub-problems?

- given  $j$ , what is the fastest way to get thro'  $S_{1,j}$
- given  $j$ , what is the fastest way to get thro'  $S_{2,j}$

Definitions:

- $f_1[j]$  = the fastest time to get thro'  $S_{1,j}$
- $f_2[j]$  = the fastest time to get thro'  $S_{2,j}$

The final solution equals to  $\min \{ f_1[n], f_2[n] \}$

Task:

- Starting from  $f_1[1]$  and  $f_2[1]$ , compute  $f_1[j]$  and  $f_2[j]$  incrementally

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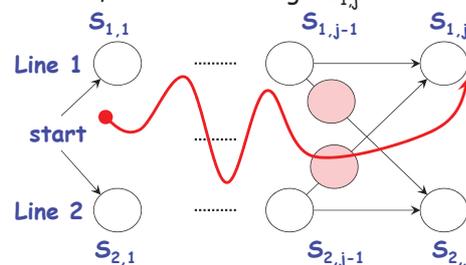
(Dynamic Programming)

# Solving the sub-problems (1)

**Q1:** what is the fastest way to get thro'  $S_{1,j}$ ?

**A:** either

- the fastest way thro'  $S_{1,j-1}$ , then **directly** to  $S_{1,j}$ , or
- the fastest way thro'  $S_{2,j-1}$ , a **transfer** from line 2 to line 1, and then through  $S_{1,j}$



40

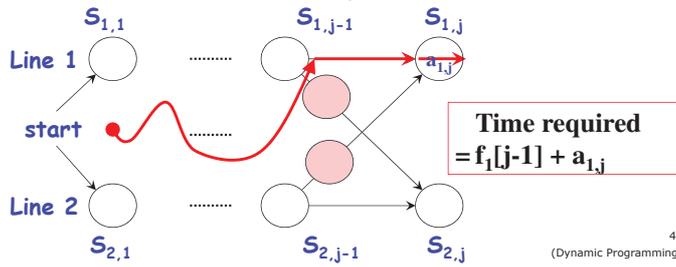
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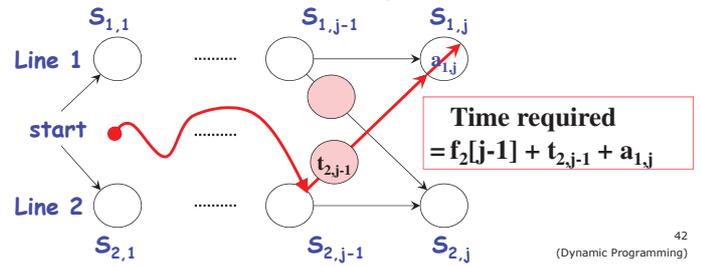
41

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42

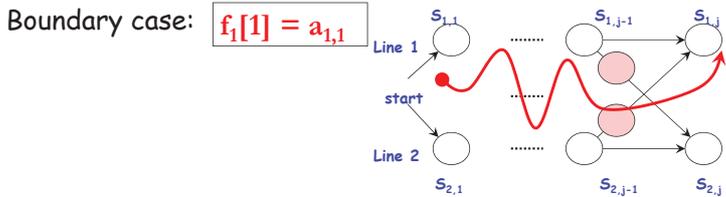
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- > the fastest way thro'  $S_{2,j-1}$ , a transfer from line 2 to line 1, and then through  $S_{1,j}$

Conclusion:  $f_1[j] = \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j})$



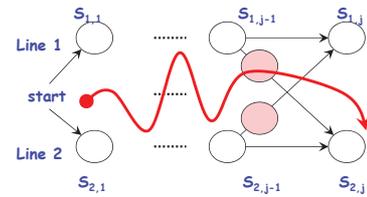
## Solving the sub-problems (2)

Q2: what is the fastest way to get thro'  $S_{2,j}$ ?

By exactly the same analysis, we obtain the formula for the fastest way to get thro'  $S_{2,j}$ :

$$f_2[j] = \min(f_2[j-1] + a_{2,j}, f_1[j-1] + t_{1,j-1} + a_{2,j})$$

Boundary case:  $f_2[1] = a_{2,1}$



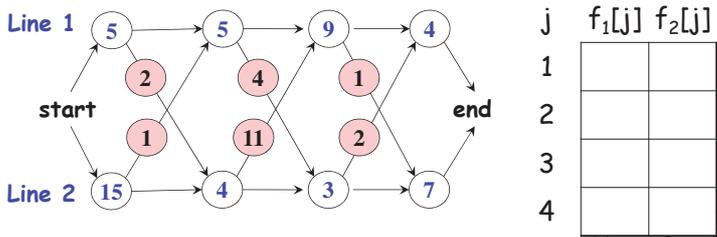
44

## Summary

$$f_1[j] = \begin{cases} a_{1,1} & \text{if } j=1, \\ \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j}) & \text{if } j>1 \end{cases}$$

$$f_2[j] = \begin{cases} a_{2,1} & \text{if } j=1, \\ \min(f_2[j-1] + a_{2,j}, f_1[j-1] + t_{1,j-1} + a_{2,j}) & \text{if } j>1 \end{cases}$$

$$f^* = \min(f_1[n], f_2[n])$$

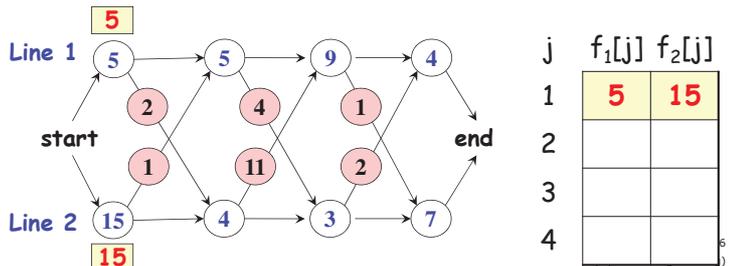


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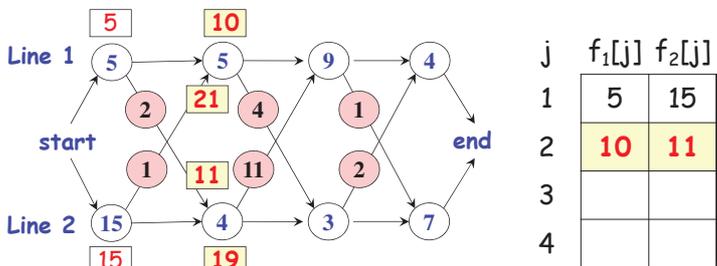


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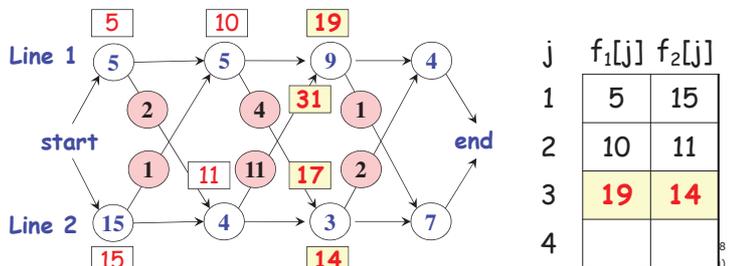


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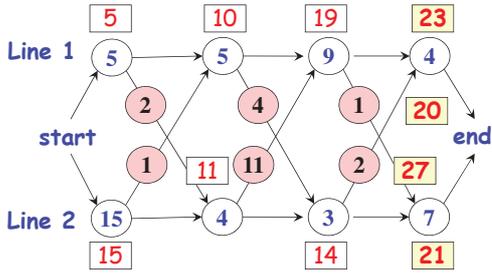


# Summary

$$f_1[j] = \begin{cases} a_{1,1} & \text{if } j=1, \\ \min(f_1[j-1]+a_{1,j}, f_2[j-1]+t_{2,j-1}+a_{1,j}) & \text{if } j>1 \end{cases}$$

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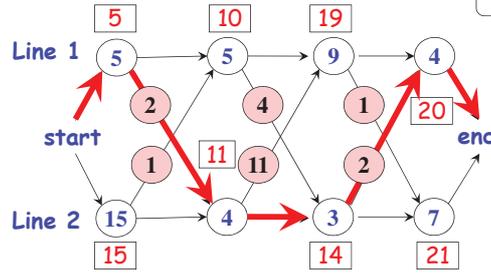
j	f <sub>1</sub> [j]	f <sub>2</sub> [j]
1	5	15
2	10	11
3	19	14
4	20	21

# Summary

$$f_1[j] = \begin{cases} a_{1,1} & \text{if } j=1, \\ \min(f_1[j-1]+a_{1,j}, f_2[j-1]+t_{2,j-1}+a_{1,j}) & \text{if } j>1 \end{cases}$$

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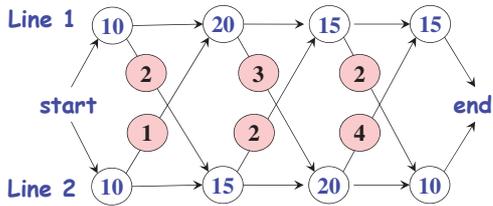
$$f^* = \min(f_1[n], f_2[n])$$



**f\* = 20**

j	f <sub>1</sub> [j]	f <sub>2</sub> [j]
1	5	15
2	10	11
3	19	14
4	20	21

# Exercise



j	f <sub>1</sub> [j]	f <sub>2</sub> [j]
1		
2		
3		
4		

# Pseudo code

set f<sub>1</sub>[1] = a<sub>1,1</sub>

set f<sub>2</sub>[1] = a<sub>2,1</sub>

for j = 2 to n do

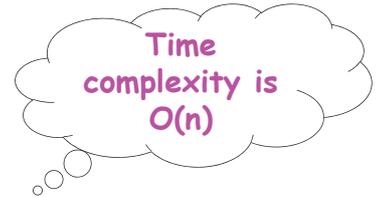
begin

set f<sub>1</sub>[j] = min ( f<sub>1</sub>[j-1]+a<sub>1,j</sub> , f<sub>2</sub>[j-1]+t<sub>2,j-1</sub>+a<sub>1,j</sub> )

set f<sub>2</sub>[j] = min ( f<sub>2</sub>[j-1]+a<sub>2,j</sub> , f<sub>1</sub>[j-1]+t<sub>1,j-1</sub>+a<sub>2,j</sub> )

end

set f\* = min ( f<sub>1</sub>[n] , f<sub>2</sub>[n] )



# What about 3 assembly lines?