## Brief Announcement: Decidable Graph Languages by Mediated Population Protocols<sup>\*</sup>

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Abstract. We work on an extension of the Population Protocol model of Angluin et al. [1] that allows edges of the communication graph, G, to have states that belong to a constant size set. In this extension, the so called Mediated Population Protocol model (MPP) [2,3], both uniformity and anonymity are preserved. We here study a simplified version of MPP, the Graph Decision Mediated Population Protocol model (GDM), in order to capture MPP's ability to decide graph languages. We also prove some first impossibility results both for weakly connected and possibly disconnected communication graphs.

## 1 The GDM model

A graph decision mediated population protocol (GDM)  $\mathcal{A}$  consists of a binary output alphabet  $Y = \{0, 1\}$ , a finite set of agent states Q, an agent output function  $O: Q \to Y$  mapping agent states to outputs, a finite set of edge states S, an output instruction r, a transition function  $\delta: Q \times Q \times S \to Q \times Q \times S$ , an initial agent state  $q_0$ , and an initial edge state  $s_0$ .

Let  $\mathcal{U}$  denote a graph universe, that is, any set of communication graphs. A graph language L is a subset of  $\mathcal{U}$  containing communication graphs sharing some common property. For example, a common graph universe is the set of all possible directed and weakly connected communication graphs, denoted by  $\mathcal{G}$ , and  $L = \{G \in \mathcal{G} \mid |E(G)| \text{ is even}\}$  is a possible graph language w.r.t.  $\mathcal{G}$ .

A GDM protocol may run on any graph from a specified graph universe. The graph on which the protocol runs is considered as the *input graph* of the protocol. Note that GDM protocols have no sensed input. Instead, we require each agent in the population to be initially in the initial agent state  $q_0$  and each edge of the communication graph to be initially in the initial edge state  $s_0$ . So, the initial network configuration,  $C_0$ , of any GDM is defined as  $C_0(u) = q_0$ , for all  $u \in V$ , and  $C_0(e) = s_0$ , for all  $e \in E$ , and any input graph G = (V, E).

We say that a GDM  $\mathcal{A}$  accepts an input graph G if in any computation of  $\mathcal{A}$  on G after finitely many interactions all agents output the value 1 and continue

<sup>&</sup>lt;sup>\*</sup> This work has been partially supported by the ICT Programme of the European Union under contract number ICT-2008-215270 (FRONTS).

doing so in all subsequent (infinite) computational steps. By replacing 1 with 0 we get the definition of the *reject* case. A GDM  $\mathcal{A}$  decides a graph language  $L \subseteq \mathcal{U}$  if it accepts any  $G \in L$  and rejects any  $G \notin L$ , and a graph language is said to be decidable if some GDM decides it.

**Theorem 1.** The class of decidable graph languages is closed under complement, union and intersection operations.

Node and edge parity, bounded out-degree by a constant, existence of a node with more incoming than outgoing neighbors, and existence of some directed path of length at least  $k = \mathcal{O}(1)$  are some examples of decidable graph languages, in the case where the graph universe is  $\mathcal{G}$ . Also, given that the graph universe is  $\mathcal{G}$  one can prove the following.

**Theorem 2.** There exists no GDM with stabilizing states to decide the graph language  $2C = \{G \in \mathcal{G} \mid G \text{ has at least two nodes } u, v \text{ s.t. both } (u, v), (v, u) \in E(G) \text{ (in other words, G has at least one 2-cycle)}\}.$ 

In the case where the graph universe is  $\mathcal{H}$ , containing all possible directed communication graphs (i.e. also the disconnected ones), we obtain the following strong impossibility results.

**Lemma 1.** For any nontrivial graph language L (L is nontrivial if  $L \neq \emptyset$  and  $L \neq \mathcal{H}$ ), there exists some disconnected graph G in L where at least one component of G does not belong to L or there exists some disconnected graph G' in  $\overline{L}$  where at least one component of G' does not belong to  $\overline{L}$  (or both).

**Theorem 3.** Any nontrivial graph language  $L \subset \mathcal{H}$  is undecidable by GDM.

**Corollary 1.** The graph language  $C = \{G \in \mathcal{H} \mid G \text{ is (weakly) connected}\}$  is undecidable.

*Proof.* C is a nontrivial graph language and Theorem 3 applies.

A full version of this paper is available at http://fronts.cti.gr/aigaion/?TR=80

## References

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