





# Computing Minimal Models Modulo Subset-Simulation for Modal Logics

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### (Minimal) Model Generation

#### Useful for several tasks:

- · hardware and software verification
- · fault analysis
- commonsense reasoning
- ...

They have been investigated for many logics.

# Minimality Criteria

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- domain minimality
- minimisation of a certain set of predicates
- minimal Herbrand models

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#### **Aims**

To propose a new minimality criterion for modal logics that

- · takes in consideration the semantics of models
- is generic enough to be applied to a variety of modal logics

To propose a tableau calculus for the generation of these minimal models

# **Modal Logics**

#### Syntax

$$\phi = \top \mid \bot \mid p_i \mid \neg \phi \mid \phi_1 \lor \phi_2 \mid \phi_1 \land \phi_2 \mid \langle R_i \rangle \phi \mid [R_i] \phi \mid \langle \mathcal{U} \rangle \phi \mid [\mathcal{U}] \phi$$

Semantics, 
$$M = (W, \{R_1, \dots, R_n\}, V)$$
  
 $M, u \not\models \bot$   $M, u \models \top$   
 $M, u \models p_i$  iff  $p_i \in V(u)$   
 $M, u \models \neg \phi$  iff  $M, u \not\models \phi$   
 $M, u \models \phi_1 \lor \phi_2$  iff  $M, u \models \phi_1$  or  $M, u \models \phi_2$   
 $M, u \models \phi_1 \land \phi_2$  iff  $M, u \models \phi_1$  and  $M, u \models \phi_2$   
 $M, u \models [R_i] \phi$  iff for every  $v \in W$  if  $(u, v) \in R_i$  then  $M, v \models \phi$   
 $M, u \models \langle R_i \rangle \phi$  iff there is a  $v \in W$  such that  $(u, v) \in R_i$  and  $M, v \models \phi$   
 $M, u \models \langle U \rangle \phi$  iff there is a  $v \in W$  such that  $M, v \models \phi$ 

# Why a New Minimality Criterion?

#### Domain minimal models

#### Advantages:

- models with the smallest domain
- finite models for logics with the finite model property

- models can be counter-intuitive
- hard to achieve minimal model completeness

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# Why a New Minimality Criterion? (cont'd)

#### Minimal Herbrand models

#### Advantages:

- minimisation of relations and atoms
- comparison of atoms between the same world in different models

- the criterion is syntactic
- minimal models can be infinite

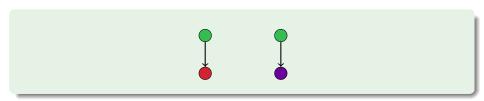
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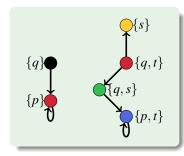
#### Disadvantages:

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□◇⊤ in a transitive and reflexive frame

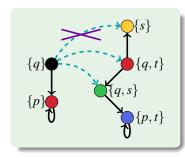
Relation between nodes of two models  $M = (W, \{R_1, \dots, R_n\}, V)$  and  $M' = (W', \{R_1, \dots, R_n\}, V')$  s.t.

- 1 the subset relationship holds  $(V(u) \subseteq V'(u'))$
- 2 successor in the first model⇒ successor in the second model
- 3 1 and 2 hold for the successors of point 2



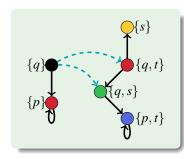
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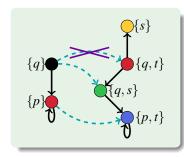
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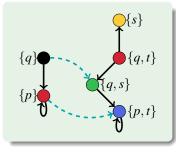
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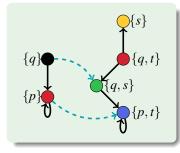


Full Subset-Simulation: for all  $u \in W$  there exists some  $u' \in W'$  s.t.  $uS \subseteq u'$ .

Maximal Subset-Simulation:  $S\subseteq$  maximal if there is no  $S'\subseteq$  s.t.  $S\subseteq\subset S'\subseteq$ .

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If there is a full and maximal subset-simulation from M to M', then M is subset-simulated by M', or M' subset-simulates M.

#### Subset-simulation is

- reflexive
- transitive

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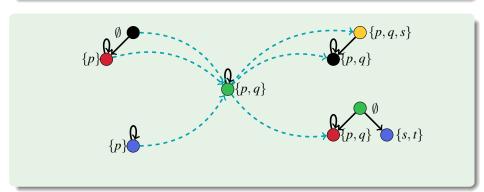
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Minimal models are the minimal elements of the preorder.



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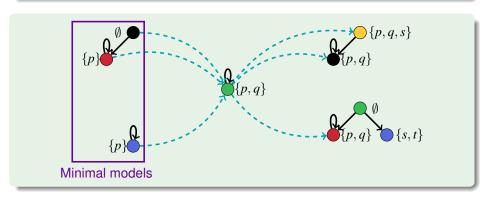
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### Too Many Minimal Models! - Symmetry Classes

#### As subset-simulation is not a partial order

- there exist symmetry classes of minimal models
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How can we make the minimality criterion stricter?

# Refining Symmetric Models – Simulation

Simulation is as subset-simulation except for the condition V(u) = V'(u').

The use of simulation among symmetric minimal models allows to

- reduce the number of minimal models
- · recognise bisimilar models

Symmetric w.r.t. subset-simulation:



The right model is simulated by the left model, but not the other way around:



### **Properties of the Minimality Criterion**

- applied to the graph representation of models (syntax independent)
- loop free models are preferred
- minimisation of the content of worlds
- · suitable for many non-classical logics

### Tableau Calculus

Input: a modal formula in negation normal form.

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#### Selection-based resolution:

- closure rule
- removes negative information from disjunctions

$$(SBR) \xrightarrow{u:p_1 \ldots u:p_n} u:\neg p_1 \vee \ldots \vee \neg p_n \vee \Phi_{\alpha}^+$$
$$u:\Phi_{\alpha}^+$$

 $\Phi_{\alpha}^{+}$ : a disjunction where no disjunct is of the form  $\neg p_{i}$ .

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### Lazy clausification:

- avoids preprocessing steps
- · can result in less inferences

$$(\alpha) \frac{u : (\phi_1 \wedge \ldots \wedge \phi_n) \vee \Phi_{\alpha}^+}{u : \phi_1 \vee \Phi_{\alpha}^+}$$

$$\vdots$$

$$u : \phi_n \vee \Phi_{\alpha}^+$$

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## Tableau Calculus (cont'd)

### Complement splitting:

- variation of the standard  $\beta$  rule
- · detects trivially non-minimal models

$$(\beta) \begin{array}{c|c} u : \mathcal{A} \vee \Phi^+ \\ \hline u : \mathcal{A} & u : \Phi^+ \\ u : neg(\Phi^+) \end{array}$$

$$\mathcal{A} ::= p \mid \langle R_i \rangle \phi \mid [R_i] \phi$$

$$neg(\Phi^+) = \neg p_1 \wedge \ldots \wedge \neg p_n$$

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Expansion of diamond formulae:

$$(\diamondsuit) \frac{u : \langle R_i \rangle \phi}{\begin{array}{c|c} (u, u_1) : R_i & \dots & (u, u_n) : R_i & (u, v) : R_i \\ u_1 : \phi & u_n : \phi & v : \phi \end{array}}$$

v is a fresh new world

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Expansion of box formulae: the standard  $\square$  rule

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#### The calculus is

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But it is not minimal model sound (generates also non-minimal models)!

### Minimal Model Soundness

Idea: incremental generation of models

Expansion strategy: the left most branch with the least number of worlds

#### Subset-simulation test:

- · early closure of "non-minimal" branches
- backward closure of branches minimal model refining

### Minimal Model Soundness

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The resulting calculus is minimal model sound and complete  $\Rightarrow$  all and only minimal models are generated.

### Subset-Simulation Test

#### Early closure of "non-minimal" branches

A partial model M subset-simulates an extracted model M', but not the other way around.

- *M* is already not minimal
- no expansion of M can be minimal
  - $\Rightarrow$  close the branch from which M is extracted

Backward closure of branches - minimal model refining

M = newly extracted model, S = current set of minimal models.

- M is not minimal
  - close the branch from which M was extracted
- for all  $M' \in S$  s.t. M' subset-simulates M, but no the other way around
  - remove all M' from S
  - close the branches from which all M' were extracted
  - add M to S
- for all  $M' \in S$  s.t. M' subset-simulates M, and M subset-simulates M'
  - check for simulation

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### Extending the Calculus

Structural rules for frame properties (reflexivity, transitivity, ...)

(4) 
$$\frac{(u,v):R_i}{(u,w):R_i} \frac{(v,w):R_i}{(u,w):R_i}$$

Rules for universal modalities ( $\langle \mathcal{U} \rangle$  and  $[\mathcal{U}]$ )

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Those extensions preserve minimal model soundness and completeness. Termination depends on the extension (logic expressiveness).

### Conclusion and Further Work

- minimality modulo subset-simualtion is
  - semantic (based on the graph representation)
  - suitable for many non-classical logics
- the tableau calculus
  - is minimal model sound and complete
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  - can be generalised to cover more expressive logics
  - does not terminate for all the logics
- efficient implementation of the calculus
- study of reasonable restrictions for reducing the search space
  - how to simplify the (♦) rule?
  - how to achieve termination for logics with the finite model property?
- generalise the minimality criterion to fragments of first-order logic